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Volume 1, 4-7 May 2004 Page(s):277 - 282 vol. 1

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2. Evolving neural network controllers

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Evolutionary Computation, 1995., IEEE International Conference on

Volume 2, 29 Nov.-1 Dec. 1995 Page(s):579 - 583 vol.2

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3. Generation of optimal fault tolerant locomotion of the hexapod robot over rough terrain using evolutionary programming

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Evolutionary Computation, 1997., IEEE International Conference on

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4. New Free Gait Generation for a Cockroach Robot

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Karalarli, E.; Erkmen, A.M.; Erkmen, I.;

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Volume 3, Apr 26-May 1, 2004 Page(s):2177 - 2182 Vol.3

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7. Fuzzy systems to solve inverse kinematics problem in robots control: application to an hexapod robots' leg

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